# Shared Memory: Virtual Shared Memory, Threads & OpenMP

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# Agenda

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Architectures of Memory Systems

### **2** Virtual Shared Memory

Memory Mapping Separated Address Space Fundamental Problems

### 3 Pthreads

Example Race Conditions and Critical Sections Locks

# OpenMP

Example Race Conditions and Critical Sections Locks



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Example Race Conditions and Critical Sections Locks



# Shared Memory vs. Distributed Memory [1]

Shared Memory



#### Distributed Memory



# Shared Memory: Uniform Memory Access System



- Same access times for all the cores
- Direct connection to a block of memory
- Relative easy to program

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# Shared Memory: Nonuniform Memory Access System



- Different access times
- Different memory locations

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# Memory: Physical Address Space [2]

A system that uses physical addressing



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# Virtual Memory: Mapping I

- A system that uses virtual addressing
- MMU Memory Management Unit



Data word

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# Virtual Memory: Mapping II



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# Virtual Memory: Mapping III



#### VIRTUAL ADDRESS

PHYSICAL ADDRESS

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# Virtual Shared Memory: Separated Address Space I



Each process has its own Virtual Address Space

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### Simplifying linking

- Allows a linker to produce fully linked executables that are independent of the ultimate location of the code and data in the physical memory
- Simplifying loading
  - Easy to load executable and shared objects into memory
- Simplifying sharing
  - Mapping to the same physical page
- Simplifying memory allocation
  - Allocation of contiguous space

# **Cache Coherence**



#### Example

x is initialized to 2
y0 is private and owned by core 0
y1, z1 are private and owned by core 1

Time	Thread 0	Thread 1
0	y0 = x;	y1 = 3 * x;
1	x = 7;	
2		z1 = 4 * x;

What is the value of z1? z1 = 4 \* 7 = 28 or z1 = 4 \* 2 = 8

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#### Snooping cache coherence

Cores share a bus. When core 0 updates the copy of x stored in its cache, it broadcasts this information across the bus. Core 1 is "snooping" the bus and it will see that x has been updated. He marks his copy of x as invalid.

#### Directory-based cache coherence

A directory stores the status of each cache line. A directory is typically distributed and each CPU/Memory pair is responsible to update the status of its own local memory. If core 0 reads a cache line in its own local cache, it writes in the directory, that he has a copy of this cache line in his local cache. When an other core modifies a variable, that lies in that cache line, the cache controller invalidates the copies in corresponding local caches.

### Example (Serial program)

As an example, suppose we want to repeatedly call a function f(i,j) and add the computed values into a vector.

# Problem: False Sharing II

#### Example (Parallel program)

```
1
    /* Private variable */
    int i, j, iter_count;
 2
 3
    /* Shared variables initialized by one core */
 4
    int m. n. core count:
5
    double y[m];
6
7
    iter count = m/core count:
8
9
    /* Core 0 does this */
    for (i = 0; i < iter count; i++)
10
11
             for (j = 0; i < n; i++)
12
                     v[i] += f(i, j);
13
14
    /* Core 1 does this */
15
    for (i = iter_count + 1; i < 2 * iter_count; i++)</pre>
16
             for (j = 0; i < n; i++)
17
                     v[i] += f(i,i):
```

► m = 8

- doubles are 8 bytes
- cache line can store eight doubles (64 bytes)

y takes one full cache line

What happens?

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Example Race Conditions and Critical Sections Locks



- Pthreads POSIX threads
- Specifies a library for Unix-like systems
- It exists other specifications like: Java threads, Windows threads, Solaris threads. All of the specifications support the same basic ideas.

# Pthreads: Forking and Joining



- Threads are often called light-weight processes
- Master thread forks slave threads
- Slave threads joins to the master thread
- Typical approaches to thread startup:
  - ► Static threads: all threads are created before computation
    - Example: Computation of scalar product
  - Dynamic threads: threads are created at demand
    - Example: Web server applications, that responds to client requests

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```
1 #include <stdio.h>
2 #include <stdio.h>
3 #include <stdib.h>
4
5 /* Global variable: accessible to all threads */
6 int thread_count;
7
8 void *Hello(void* rank); /* Thread function */
```

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```
int main(int argc, char* argv[]) {
1
2
        long
                  thread: /* Use long in case of a 61-bit system */
3
        pthread_t* thread_handles;
4
5
       /* Get number of threads from command line */
6
        thread_count = strtol(argv[1], NULL, 10);
7
8
        thread handles = malloc (thread count*sizeof(pthread t)):
9
10
        for (thread = 0; thread < thread_count; thread++)</pre>
11
           pthread_create(&thread_handles[thread], NULL, Hello, (void*) thread);
12
13
        printf("Hello_from_the_main_thread\n");
14
15
        for (thread = 0: thread < thread count: thread++)</pre>
16
           pthread_join(thread_handles[thread], NULL);
17
18
        free(thread handles):
19
        return 0:
20
       /* main */
```

```
1
2
3
4
5
6
7
```

```
void *Hello(void* rank) {
   long my_rank = (long) rank; /* Use long in case of 64-bit system */
   printf("Hello_from_thread_%ld_of_%d\n", my_rank, thread_count);
   return NULL;
} /* Hello */
```

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# Pthreads: Forking and Joining functions

#### Starting/forking threads

1

#### Thread function

void\* thread\_function(void\* args\_p);

### Stopping/joining threads

1 int pthread\_join( 2 pthread\_t thread, 3 void\*\* ret\_val\_p);

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# Pthreads: Example execution

#### Compilation

1 gcc -g -Wall -o pth\_hello pth\_hello.c -lpthreads

#### Execution with 1 thread

1 ./pth\_hello 1

1 Hello from the main thread 2 Hello from thread 0 of 1

#### Execution with 4 threads results in a non-deterministic output

1 ./pth\_hello 4

L	Hello	from	the	mai	in	thi	read	
2	Hello	from	thre	ad	0	of	4	
3	Hello	from	thre	ad	1	of	4	
ŧ.	Hello	from	thre	ad	2	of	4	
5	Hello	from	thre	ad	3	of	4	

1	Hello	from	thread (	)	of	4
2	Hello	from	thread 2	2	of	4
3	Hello	from	thread 1	L	of	4
4	Hello	from	the mair	ı	thr	ead
5	Hello	from	thread 3	3	of	4

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#### Race condition

When several threads attempt to access a shared resource such as a shared variable or a shared file, at least one of the accesses is an update, and the access can result in an error, we have a race condition.

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#### Example

x = x + y;

y = Compute(my\_rank);

Suppose that we have two threads. Each thread computes a value and stores it in a private variable y. We want add these both values to the shared variable x.

```
1
```

```
Time
        Thread 0
                                             Thread 1
        Started by main thread
1
2
        Call Compute()
                                             Started by main thread
3
        Assign y = 1
                                             Call Compute()
4
        Put x = 0 and y = 1 into registers
                                             Assign y = 2
5
        Add 0 and 1
                                             Put x = 0 and y = 2 into registers
6
        Store 1 in memory location x
                                             Add 0 and 2
7
                                             Store 2 in memory location x
```

The "winner" result will be overwritten by the "loser".

#### Locks

- busy-waiting
- mutexes (mutual exclusions)
- semaphores
- read-write locks

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#### Formula for computing $\pi$

$$\pi = 4\left(1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + \dots + (-1)^n \frac{1}{2n+1} + \dotsb\right)$$
(1)

#### • Serial computation of $\pi$

```
double Serial_pi(long long n) {
1
2
        double sum = 0.0;
3
       long long i;
4
        double factor = 1.0:
5
6
        for (i = 0; i < n; i++, factor = -factor) {
7
8
          sum += factor/(2*i+1);
        3
9
       return 4.0*sum;
10
       /* Serial_pi */
```

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```
1
    void* Thread_sum(void* rank) {
2
        long my_rank = (long) rank;
3
        double factor:
4
        long long i;
5
        long long my_n = n/thread_count;
6
       long long my_first_i = my_n*my_rank;
7
        long long my_last_i = my_first_i + my_n;
8
9
        if (my_first_i % 2 == 0)
10
          factor = 1.0;
11
        else
12
          factor = -1.0;
13
14
        for (i = my_first_i; i < my_last_i; i++, factor = -factor) {</pre>
15
          sum += factor/(2*i+1); // Critical Section
16
        3
17
18
        return NULL;
19
       /* Thread_sum */
    3
```

#### "Concept of Busy-Waiting"

```
1  y = Compute(my_rank);
2  while = (flag != my_rank);
3  x = x + y;
4  flag++;
```

- Thread keep re-executing the test until the test is false
- Simple implementation with a busy-wait loop
- Programmer can control the order of execution of threads
- Consumes CPU cycles
- Can seriously degrade performance

```
void* Thread sum(void* rank) {
1
2
        long my_rank = (long) rank;
3
        double factor, my_sum = 0.0;
4
        long long i:
5
        long long my_n = n/thread_count;
6
        long long my_first_i = my_n*my_rank;
7
        long long my_last_i = my_first_i + my_n;
8
9
        if (my_first_i % 2 == 0)
10
           factor = 1.0;
11
        else
12
           factor = -1.0:
13
14
        for (i = my_first_i; i < my_last_i; i++, factor = -factor)</pre>
15
           mv_sum += factor(2*i+1):
16
17
       while (flag != my_rank);
18
       sum += my_sum;
19
       flag = (flag+1) % thread_count;
20
21
        return NULL:
22
       /* Thread sum */
    }
```

- Abbreviation of mutual exclusions
- A mutex is a special type of a variable

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# Pthreads: Mutexes

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A variable of type pthread\_mutex\_t needs to be initialized before it (a mutex) can be used.

Initialization of a mutex

#### Destruction of a mutex

- 1 int pthread\_mutex\_destroy(pthread\_mutex\_t\* mutex\_p);
- Gain access to a critical section
- 1 int pthread\_mutex\_lock(pthread\_mutex\_t\* mutex\_p);

#### Unlock critical section

1 int pthread\_mutex\_unlock(pthread\_mutex\_t\* mutex\_p);

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# Pthreads: Semaphores

- Semaphores can be thought as a special type of unsigned int
  - ▶ They can take values 0, 1, 2, ...
  - Binary semaphore takes 0 and 1 as values
  - ► Value 0 means "locked" and 1 means "unlocked"
- Semaphores are not a part of Pthreads and it's necessary to add the following preprocessor directive:

1 #include <semaphore.h>

It's possible to control the order in which the threads execute the critical section

# Pthreads: Semaphores in C-Language

A variable of type sem\_t needs to be initialized before it (a semaphore) can be used.

Initialization of a semaphore

```
1 int sem_init(
2 sem_t* semaphore_p,
3 int shared,
4 unsigned initial_val);
```

Destruction of a mutex

int sem\_destroy(sem\_t\* semaphore\_p);

Increment semaphore

```
int sem_post(sem_t* semaphore_p);
```

#### Decrement semaphore

int sem\_wait(sem\_t\* semaphore\_p);

1

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- Low-level locking
- Provides two lock-functions
  - One lock function locks the read-write lock for reading
  - ▶ The other lock function locks the read-write lock for writing

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# Pthreads: Read-Write Locks in C-Language

A variable of type pthread\_rwlock\_t needs to be initialized before it (a rwlock) can be used.

Initialization of rwlock

1 2 3

1

1

1

#### Destruction of rwlock

int pthread\_rwlock\_destroy(pthread\_rwlock\_t\* rwlock\_p);

Read-write lock for reading

1 int pthread\_rwlock\_rdlock(pthread\_rwlock\_t\* rwlock\_p);

Read-write lock for writing

int pthread\_rwlock\_rwlock(pthread\_rwlock\_t\* rwlock\_p);

### Unlock

int pthread\_rwlock\_unlock(pthread\_rwlock\_t\* rwlock\_p);

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Example Race Conditions and Critical Sections Locks



- Standard for programming shared memory systems
- Uses library functions and preprocessor directives (pragmas)
- Requires compiler support
- Developers could incrementally parallelize existing serial programs
- Higher-level than Pthreads

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# **OpenMP: Example I**

```
#include <stdio.h>
1
2
    #include <stdlib.h>
3
    #include <omp.h>
4
5
    void Hello(void); /* Thread function */
6
7
    int main(int argc, char* argv[]) {
8
        int thread count = strtol(argv[1], NULL, 10);
9
10
    # pragma omp parallel num_threads(thread_count)
11
       Hello():
12
13
       return 0:
14
    } /* main */
15
16
    void Hello(void) {
17
        int mv rank = omp_get_thread_num();
        int thread_count = omp_get_num_threads();
18
19
20
        printf("Hello, from, thread, %d, of, %d\n", my_rank, thread_count);
21
22
    3
       /* Hello */
```

# OpenMP: Example II

- Compilation
- 1  $|gcc -g -Wall -fopenmp o omp_hello omp_hello.c$

1 ./omp\_hello 4

Output is non-deterministic

1	Hello	from	thread	0	of	4
2	Hello	from	thread	1	of	4
3	Hello	from	thread	2	of	4
4	Hello	from	thread	3	of	4

1	Hello	from	thread	1	of	4
2	Hello	from	thread	2	of	4
3	Hello	from	thread	0	of	4
4	Hello	from	thread	3	of	4

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OpenMP pragmas always begin with **#** pragma omp. They are followed by a directive. Strings after a directive are called clauses. Clauses provide additional information for the directive.

#### Example

```
1
```

```
pragma omp parallel num_threads(thread_count)
Hello();
```

- The parallel directive specifies, that the structured block of code that follows should be executed by multiple threads
- The clause num\_threads(thread\_count) specifies how many threads of the structured block below should be created

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- #include <omp.h> provides predefined constants and OpenMP functions
  - int omp\_get\_thread\_num(void); returns the ID of the current thread
  - int omp\_get\_num\_threads(void); returns the number of threads in the team
- #include omp.h is only needed, if we use predefined constants or call OpenMP functions

# Race Conditions and Critical Sections

Race Condition: multiple threads are attempting to access a shared resource, at least one of the accesses is an update, and the accesses can result in an error.

Example						
Time	Thread 0	Thread 1				
0	<pre>global_result = 0 to register</pre>	finish my_result				
1	<pre>my_result = 1 to register</pre>	<pre>global_result = 0 to register</pre>				
2	add my_result to global_result	<pre>my_result = 2 to register</pre>				
3	<pre>store global_result = 1</pre>	add my_result to global_result				
4		<pre>store global_result = 2</pre>				

1

pragma omp critical
 global\_result = my\_result;

- Only one thread can execute after # pragma omp critical following structured block of code.
- No other thread can start execute this code until the first thread has finished.

- # pragma omp critical
- # pragma omp atomic
- Lock-functions in omp.h

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# 1 # pragma omp critical(name) 2 <structured block>

 Blocks protected with critical directives with different names can be executed simultaneously.

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1	#	pragma	$\verb"omp"$	ato	omi	. C	
2		~	<sing< th=""><th>le</th><th>С</th><th>assignment</th><th><pre>statement&gt;</pre></th></sing<>	le	С	assignment	<pre>statement&gt;</pre>

- Can only protect critical sections that consist of a single C assignment statement.
- Statement must ave one of the following form:

- ▶ x++;
- ► ++x;
- ▶ x--;
- ► --x;
- <op> can be one of the binary operators:
  - ▶ +, \*, -, /, &, ^, |, <<, >>
- <expression> must not reference x

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A variable of type omp\_lock\_t needs to be initialized before it (a lock) can be used.

#### Initialization

1 void omp\_init\_lock(omp\_lock\_t\* lock\_p);

Set lock

1 void omp\_set\_lock(omp\_lock\_t\* lock\_p);

#### Unset lock

1 void omp\_unset\_lock(omp\_lock\_t\* lock\_p);

#### Destroy lock

1 void omp\_destroy\_lock(omp\_lock\_t\* lock\_p);

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- 1 reduction(<operator>: <variable list>)
  - ► <operator> can be +, \*, -, &, |, ^, &&, ||
  - OpenMP creates for each variable in variable list a private variable and stores there the result of computation
  - OpenMP creates a critical section, where the results from the private variables are computed with the corresponding variable

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#### Example

#### Code without reduction clause:

#### Equivalent code with reduction clause:

1 2 3

#

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OpenMP provides many more other directives, clauses and library functions.

- Parallelization of for-loops
- Barriers and condition variables

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  - Problems: cache coherence and false sharing
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  - Example
  - Race conditions
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