

I/O Requirements for Exascale Post-Processing



Kitware

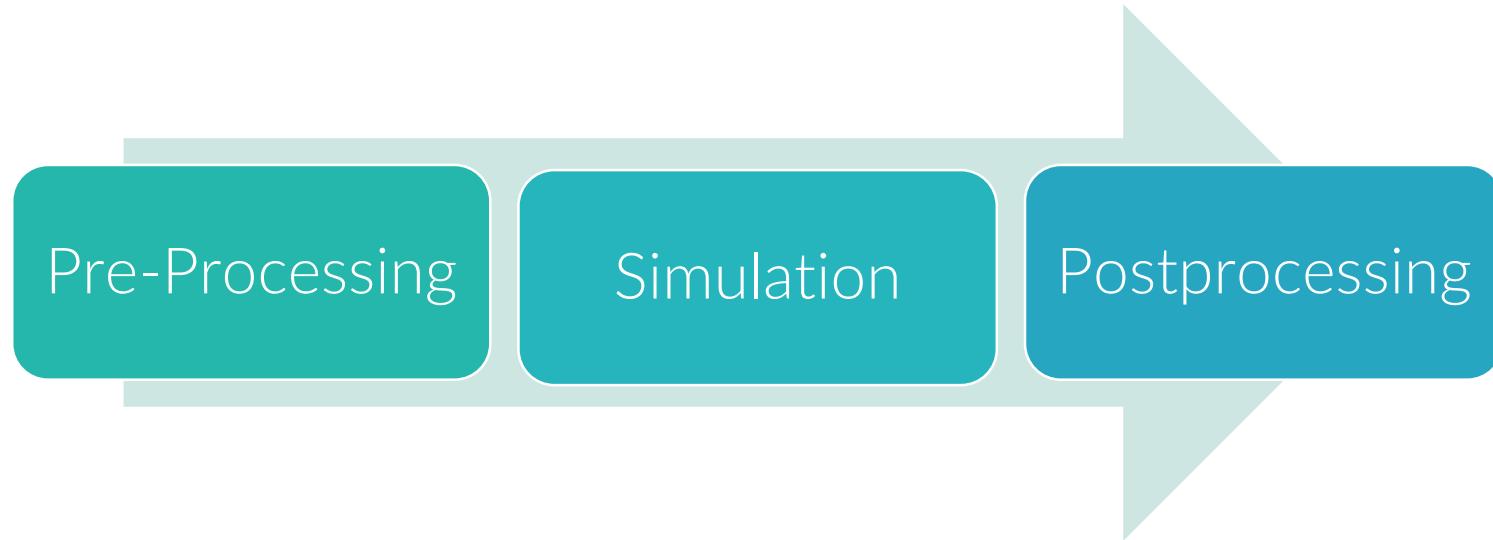
>25.09.2017

Workshop on Exascale I/O for Unstructured Grid
Hamburg, Germany

Julien Jomier – julien.jomier@kitware.com

>A WORLD WITHOUT (I/O) LIMITATIONS

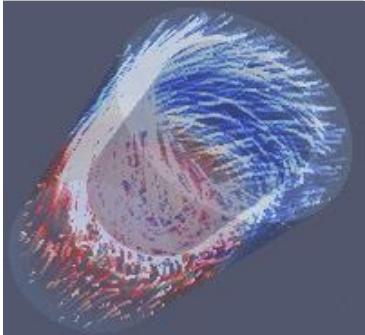
>>Let's imagine



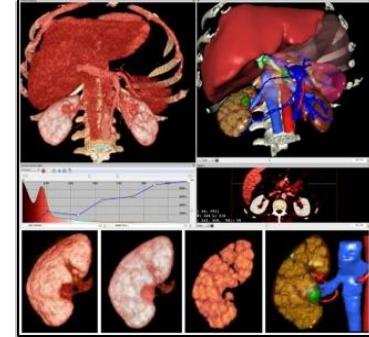
Processing any data size, instantaneously and interactively



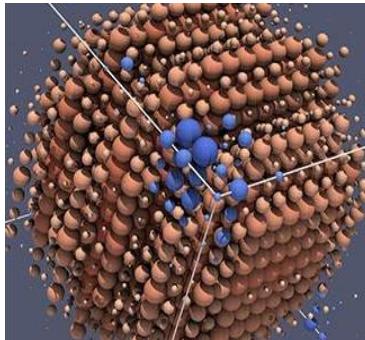
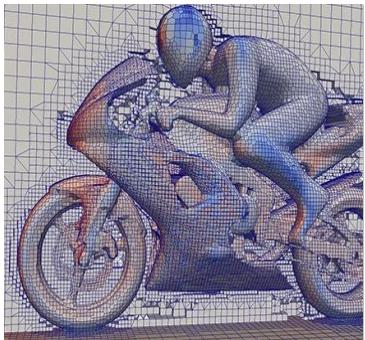
>>Open-Source Library for Scientific Visualization



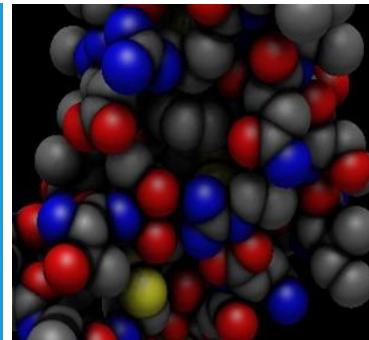
CROSS-PLATFORM VISUALIZATION LIBRARY



>> Visualization tools for scientific datasets
>> Advanced algorithms for data analysis
>> 3D Interactive Widgets



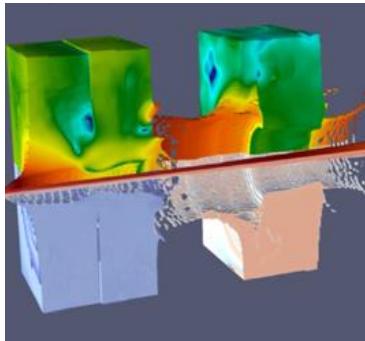
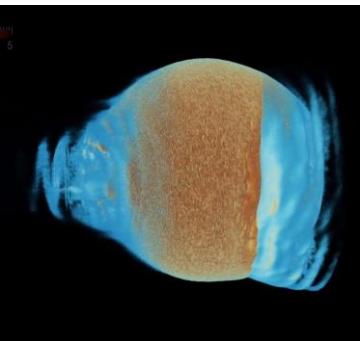
>> 25 years of development
>> BSD License



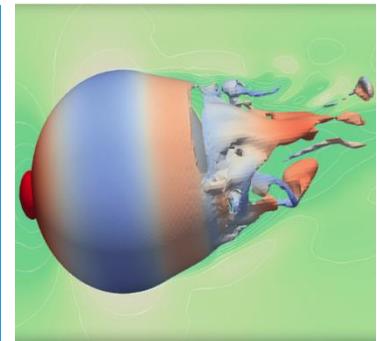
www.vtk.org

> **ParView**

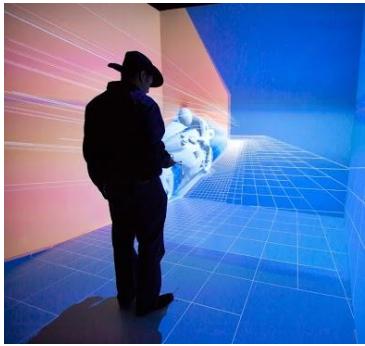
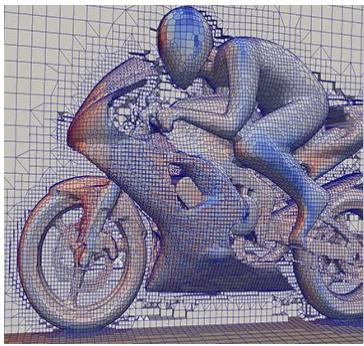
>> High performance Post-Processing



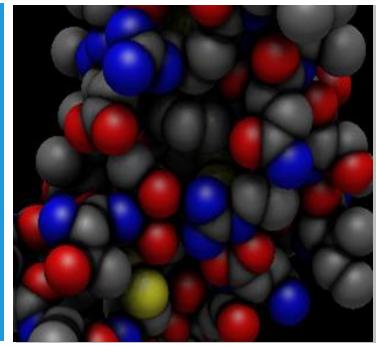
**CROSS-PLATFORM
OPEN-SOURCE
POST-PROCESSING
APPLICATION**



- >> Parallel Visualization
- >> Advanced post-processing algorithms
- >> 3D Interactive widgets
- >> In-situ processing



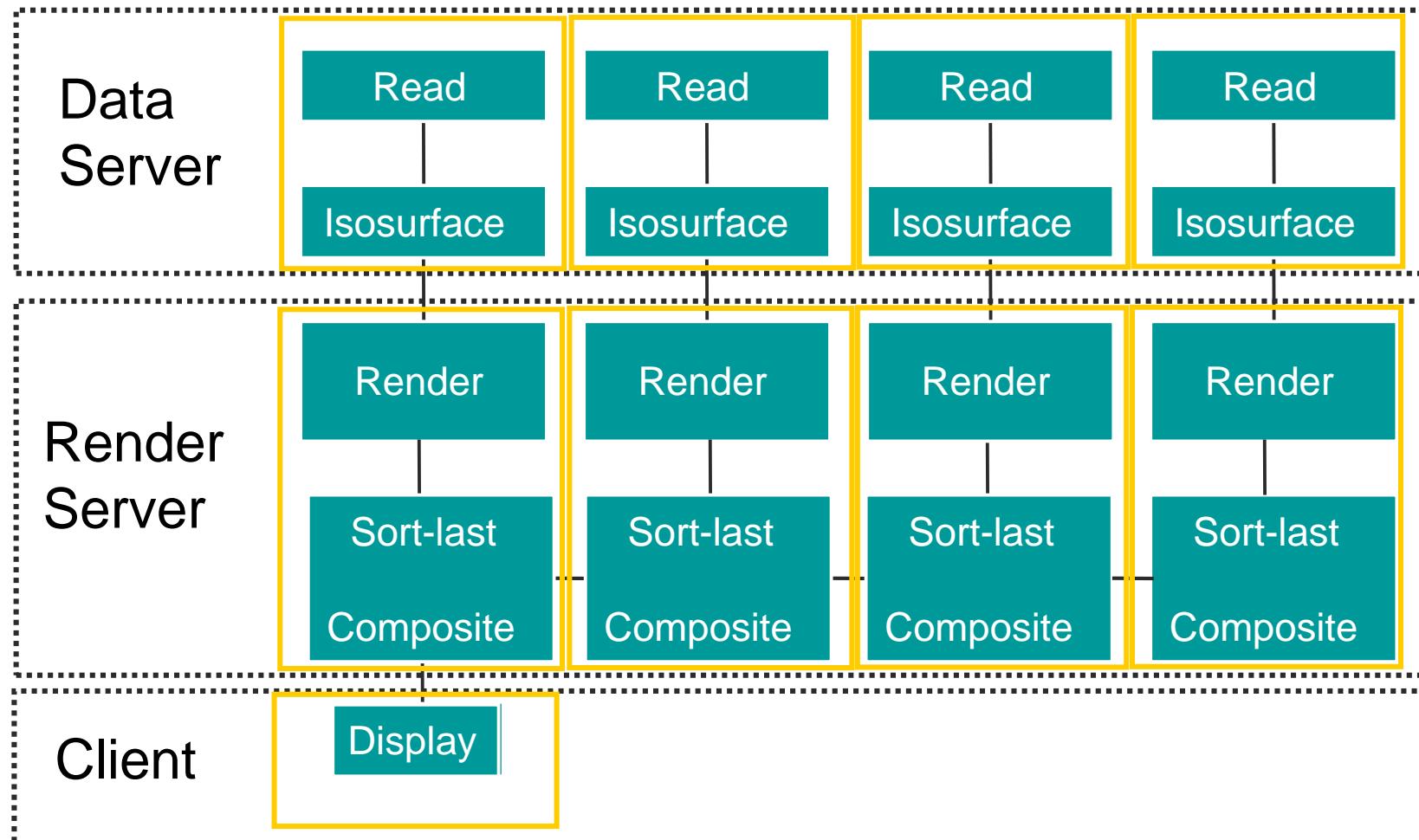
- >> 20 years of development
- >> Based on VTK
- >> License BSD



www.paraview.org

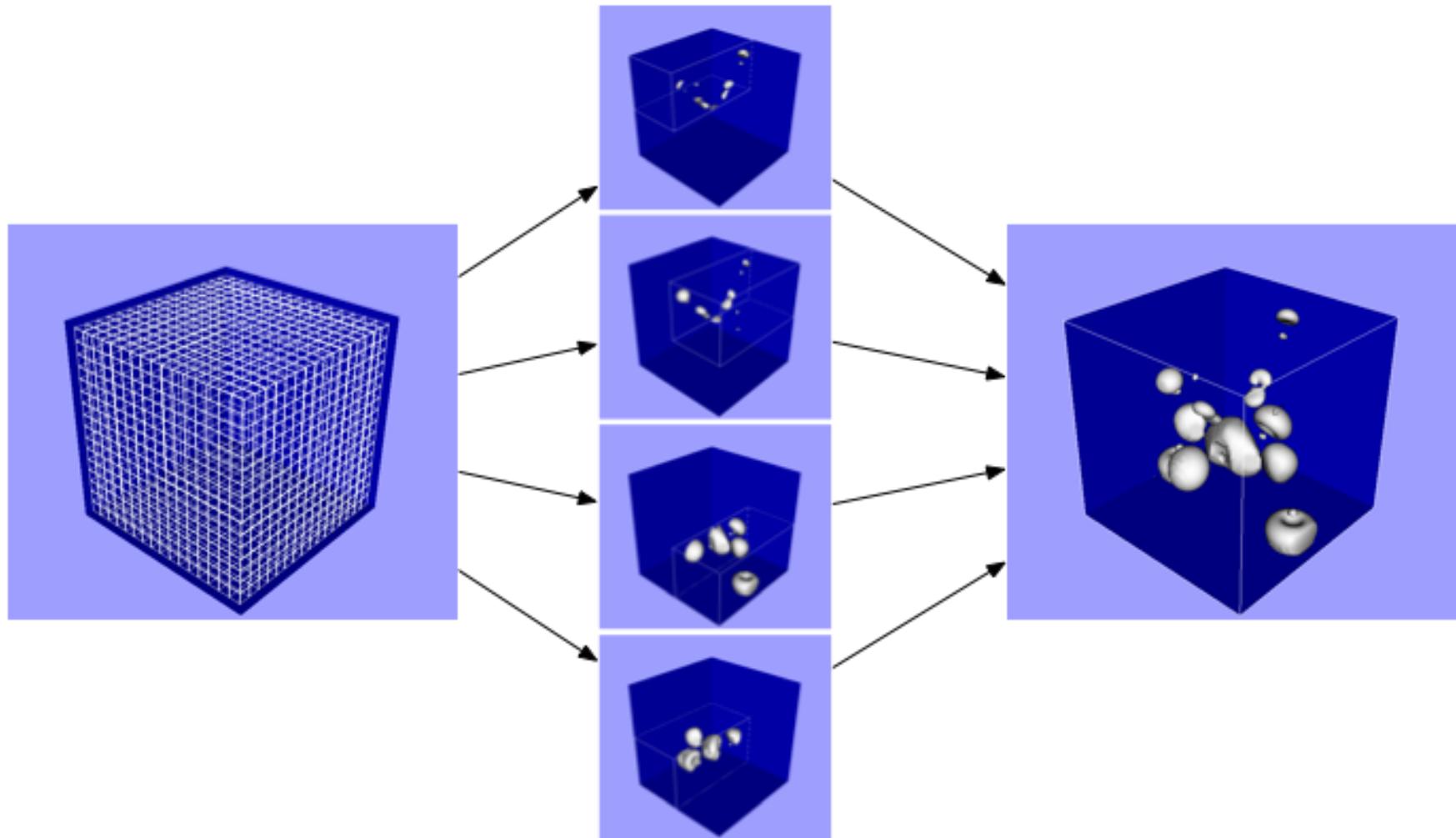
>DATA PARALLEL PIPELINE

>>In ParaView



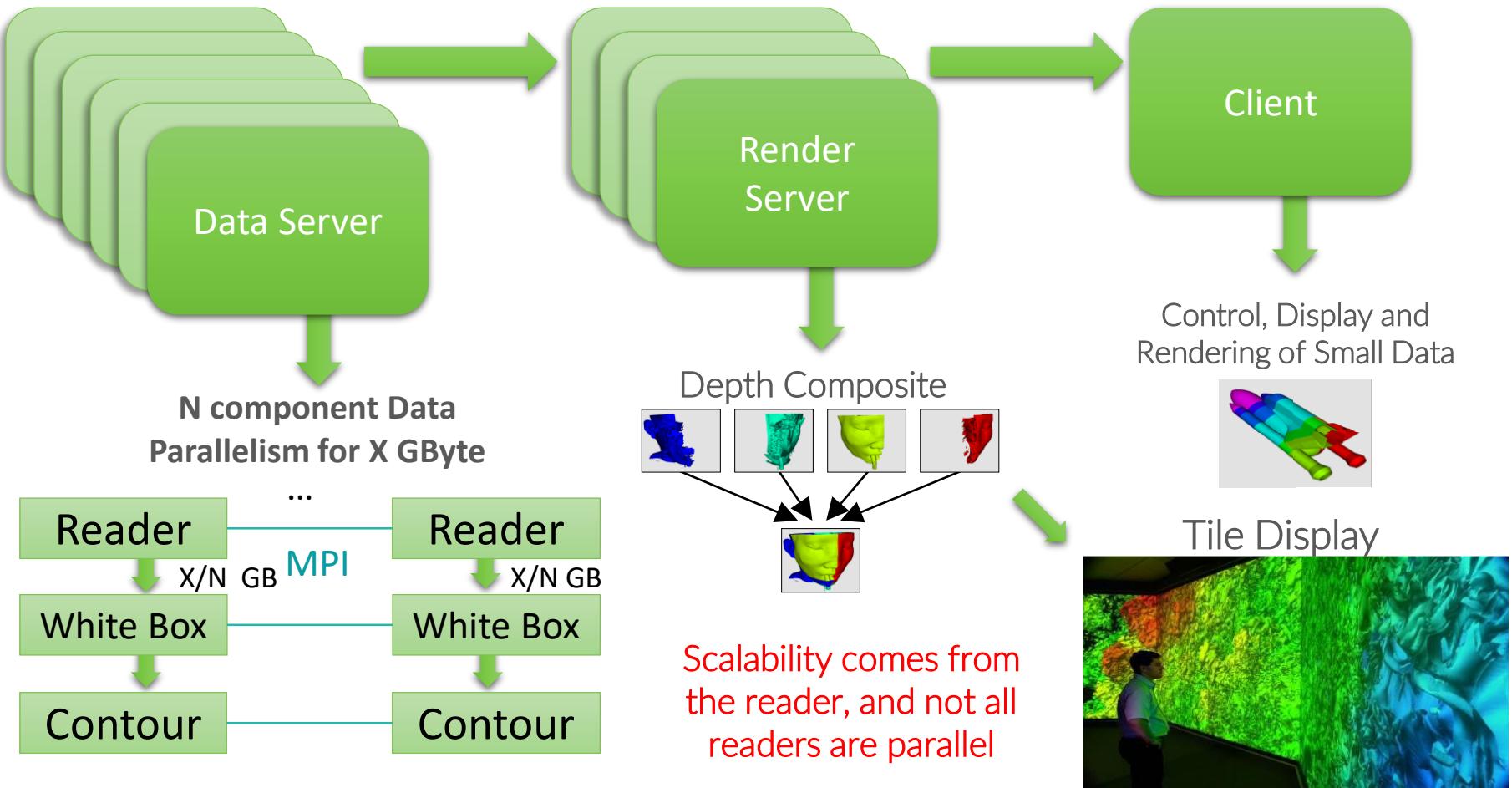
>PARALLEL PROCESSING

>>In ParaView



>PARAVIEW SCALABILITY

>>Large interactive post-processing



>PARALLEL I/O FORMATS

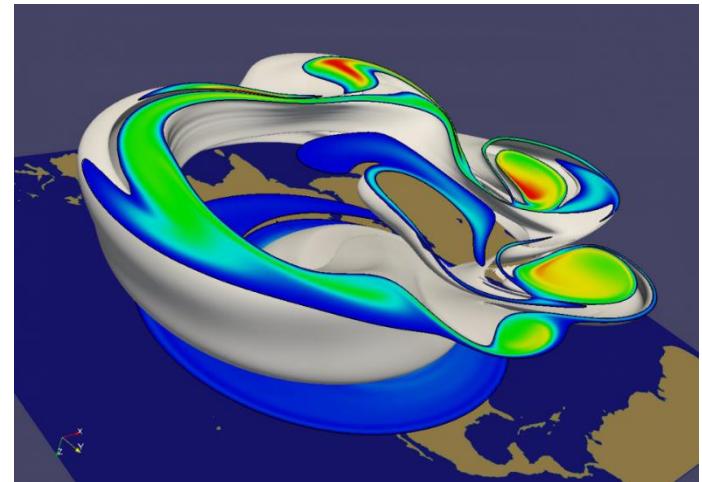
>> In VTK and ParaView

- ADIOS
- HDF5
- Exodus
- PVD
- Parallel VTK
- Ensight
- SPC TH
- LSDyna
- NetCDF

>POSTPROCESSING CHALLENGES

>>Interactive Visualization

- Exploratory visualization: no apriori knowledge on what to visualize
- Division of the data: simulation vs. rendering
- Spatial vs. Temporal data
- Bound by the slowest renderer
- Post-processing algorithm in parallel
- Exporting post-processing



>100K+ CORE CHALLENGE

>> DoD High Performance Modernization Program



“Garnet”

DoD High Performance Modernization Program (HPCMP)

Engineer Research and Development Center (ERDC)

Cray XE6: 150,592 Compute Cores

Pioneer Project:

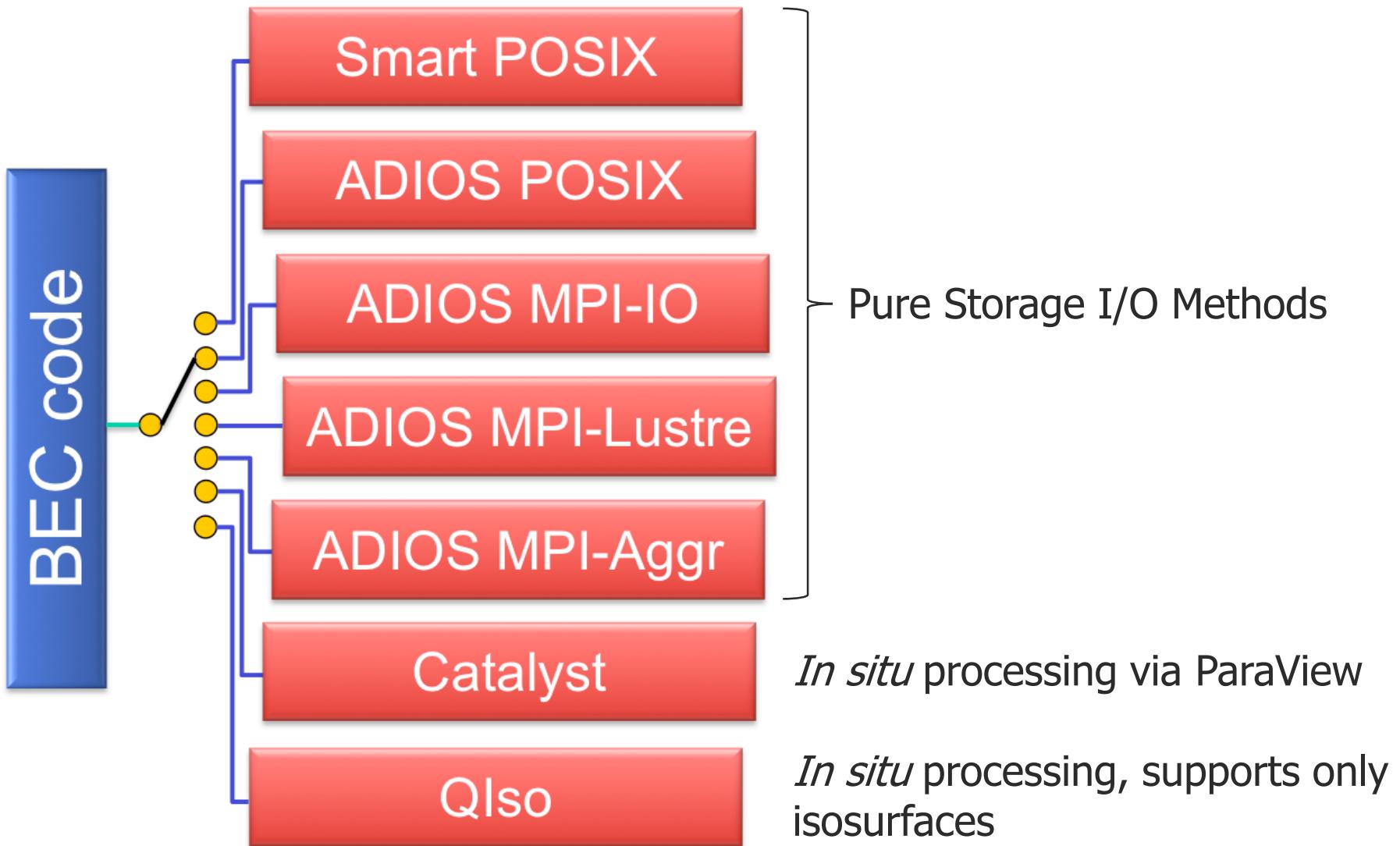
Exercise the system at entire scale (all 150K Cores)

Enable science that can only be accomplished at that scale

All-encompassing scaling: computation, communication and **I/O**

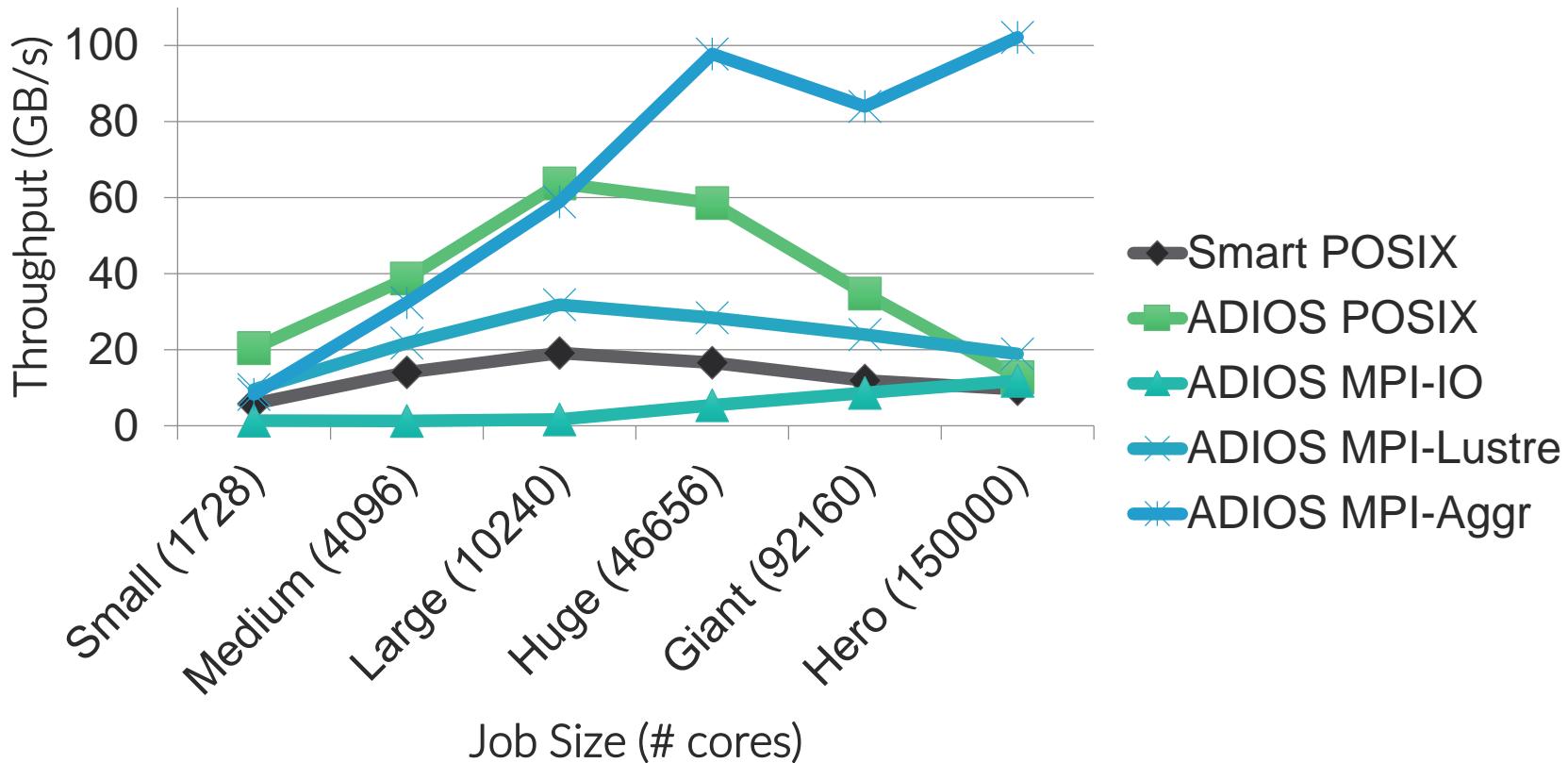
> BENCHMARKING I/O OPTIONS

>> 100K+ Core challenge



> BENCHMARK : I/O ONLY

>>100K+ Core challenge



- 2x-10x Improvement in I/O
 - depending upon scale and methods involved
- I/O is still a major bottleneck

>CHANGING FACE OF HPC

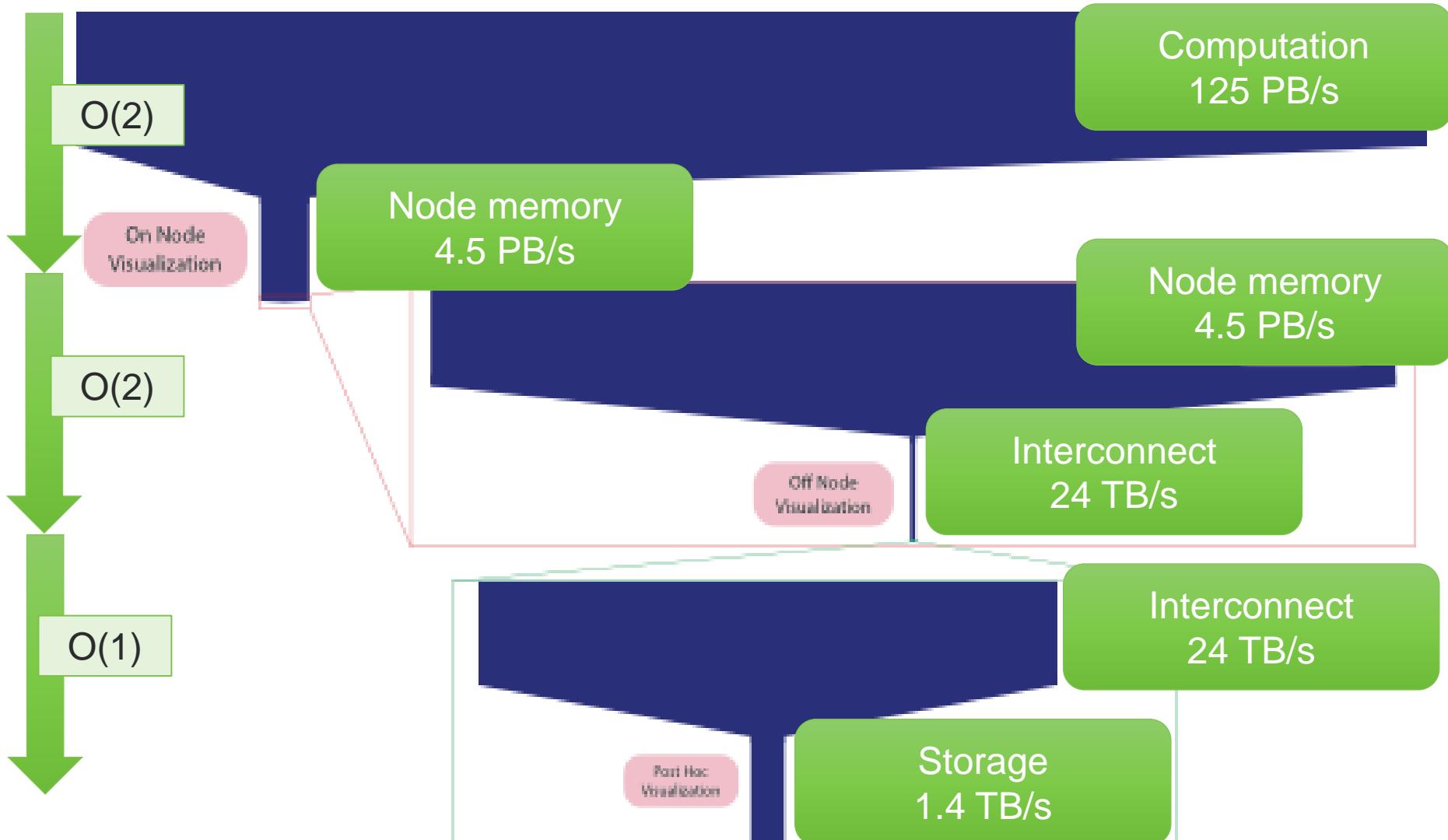
>> Oak Ridge National Laboratory

Attribute	Titan	Summit - 2018
Nodes	18,688	~4,600
Node Performance	1.4 TF	> 40 TF
Node Memory	38 GB	> 512 GB
Processor	(1) 16-core AMD Opteron	(2) IBM POWER 9s
Accelerator	(1) NVIDIA Kepler	(6) NVIDIA Volta
CPU-GPU Interconnect	PCIe2	NVLINK (5-12x PCIe3)
System Interconnect	Gemini (6.4 GB/s)	Dual Rail EDR-IB (23 GB/s)
File System	Lustre 32 PB 1 TB/s	GPFS 250 PB 2.5 TB/s
Peak Power	9 MW	15 MW

- Hierarchy of restricted/limited memory
- High latency and/or low bandwidth connections for non-traditional components
- Interconnect link saturation by the number of connected computational units
- Requiring explicit description of the fine- and coarse-grain parallelism

>COMPUTE VS I/O ON TITAN

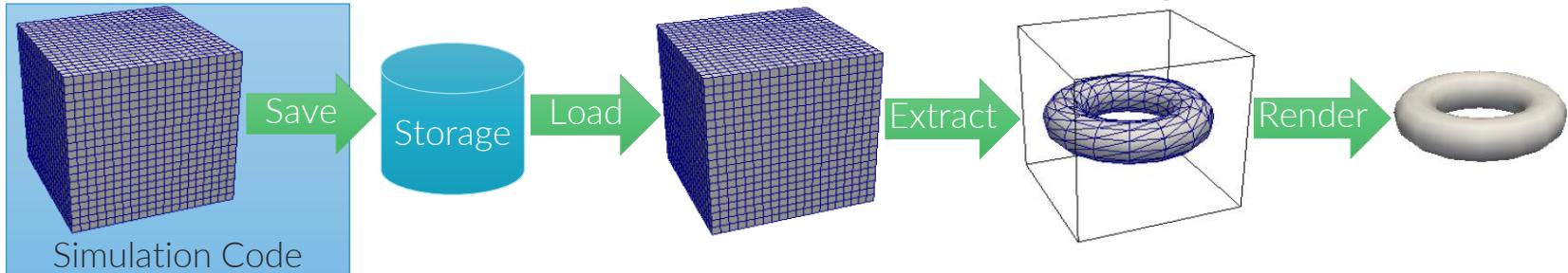
>> Oak Ridge National Laboratory



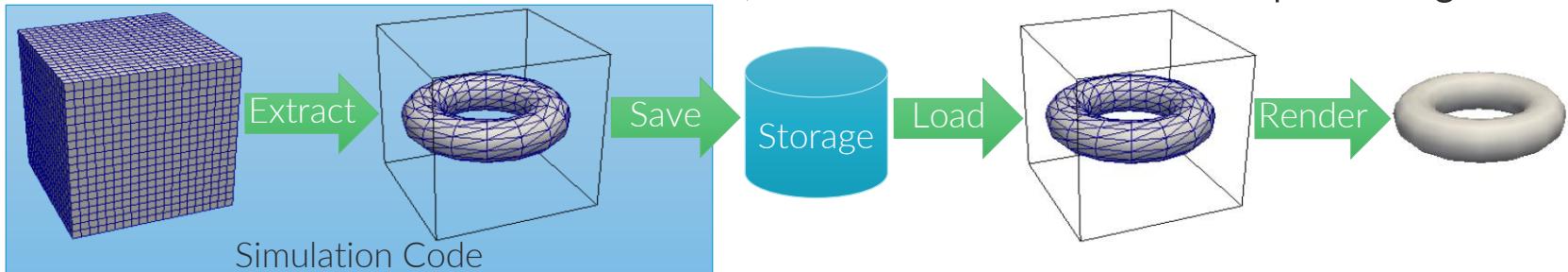
>DEALING WITH I/O BOTTLENECK

>>In-situ processing and rendering

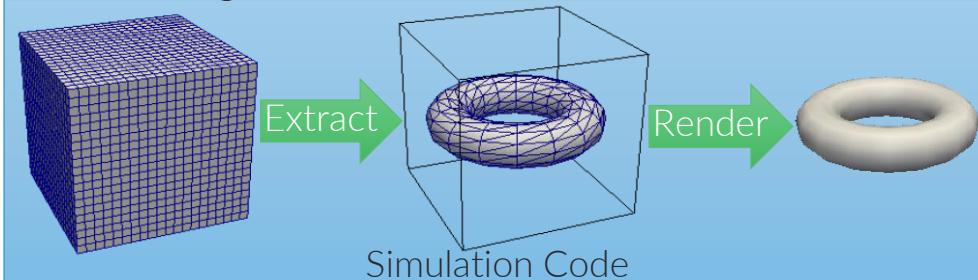
Traditional Data I/O – No, *in situ*, save all data for future processing



“Extraction *In situ*” – Extract subset of data, save the extraction for future processing



“Rendering *In situ*” – Extract subset of data and render immediately



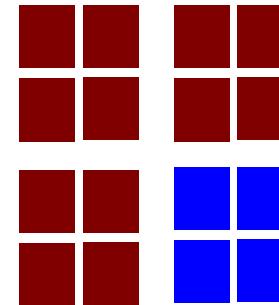
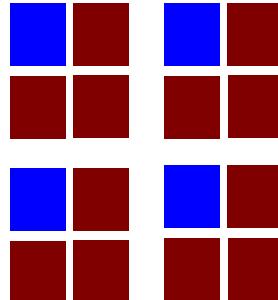
>WHAT IS IN-SITU VISUALIZATION

>> In-situ visualization

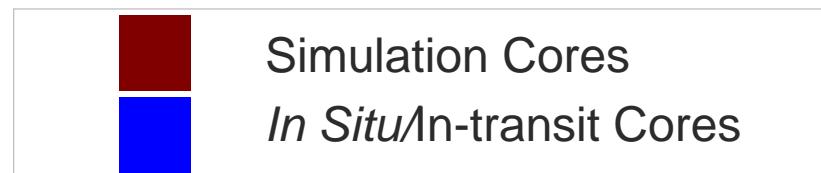
In Situ

- Many flavors/terms: tightly coupled, loosely coupled, in transit, co-processing, etc.
- Practical view: anything processed but not written to persistent storage is *in situ*

***In situ* – no data movement:**
Simulation and *in situ* methods share memory

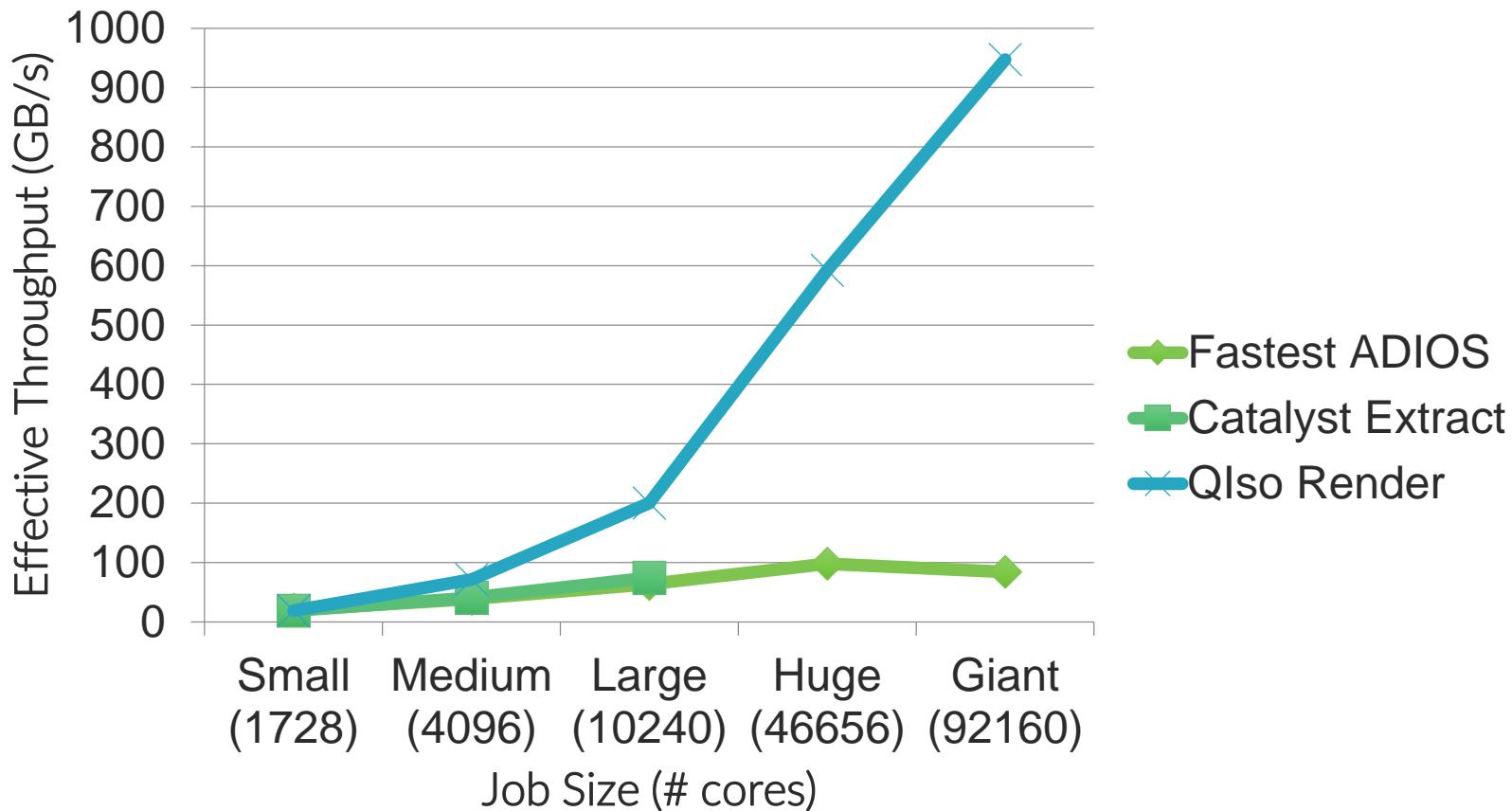


In transit – data is moved:
Simulation and *in situ* methods do not share memory



> BENCHMARK : IN SITU VS. I/O

>>100K+ Core challenge

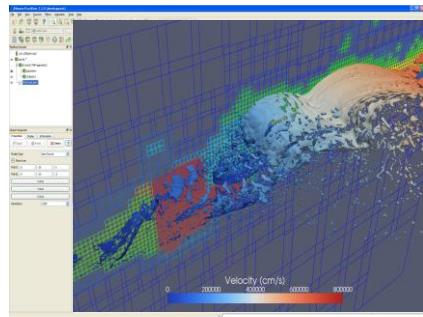


- 10x Improvement over Best I/O methods
- 100x Improvement over poor I/O methods



>CATALYST

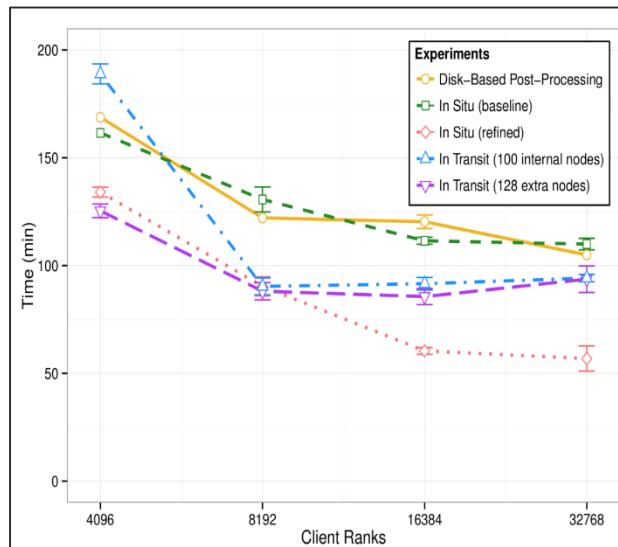
>> In-situ visualization



```
# Create the reader and set the filename.
reader = servermanager.sources.Reader(fileName="path")
view = servermanager.CreateRenderView()
repr = servermanager.CreateRepresentation(reader, view)
reader.UpdatePipeline()
dataInfo = reader.GetDataInformation()
pInfo = dataInfo.GetPointDataInformation()
arrayInfo =
    pInfo.GetArrayInformation("displacement9")

if arrayInfo:
    # get the range for the magnitude of displacement
    range = arrayInfo.GetComponentRange(-1)
    lut = servermanager.rendering.PVLookupTable()
    lut.RGBPoints = [range[0], 0.0, 0.0, 1.0,
                     range[1], 1.0, 0.0, 0.0]
    lut.VectorMode = "Magnitude"
    repr.LookupTable = lut
    repr.ColorArrayName = "displacement9"
    repr.ColorAttributeType = "POINT_DATA"
```

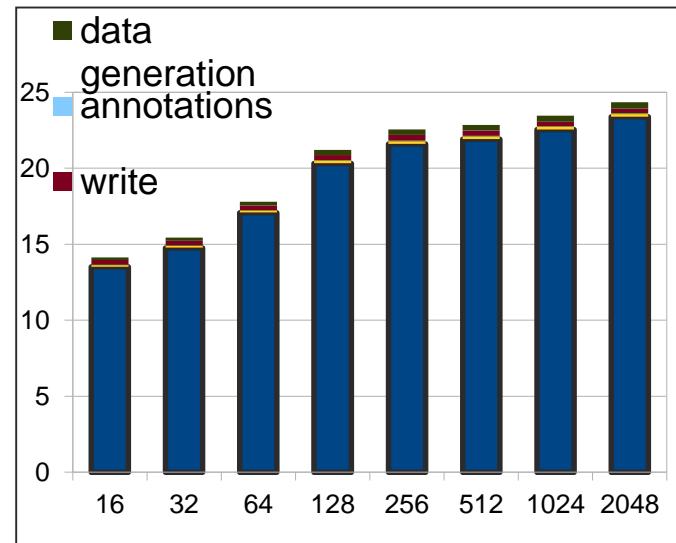
Faster Time to Solution
Than Post Hoc



Simulator Adaptor



Small Run-Time Overhead

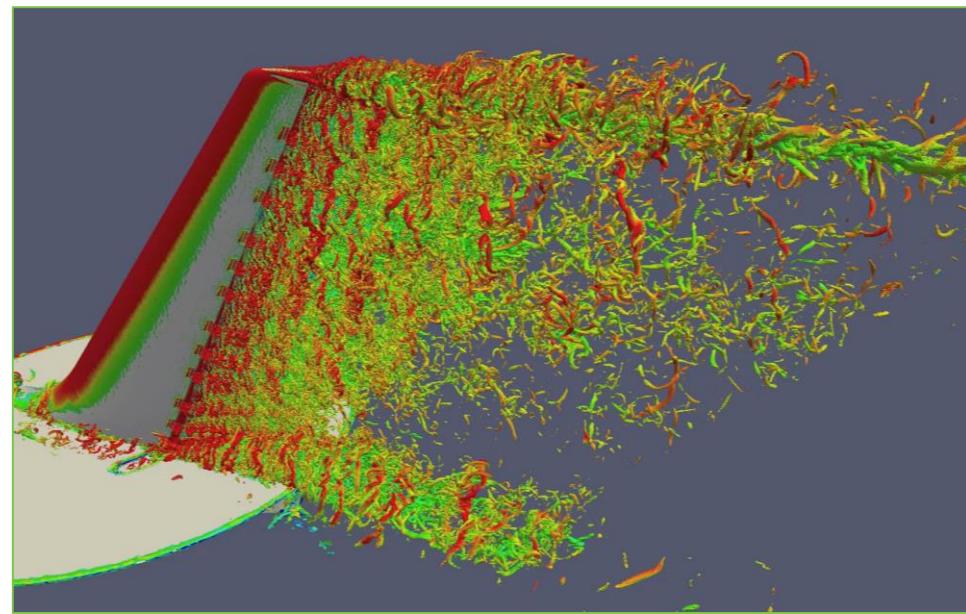


>CATALYST

>> Extreme scale use cases

- Highly scalable algorithms
- Improve Startup
 - Broadcasts scripts to other processes
- Static libraries

1M MPI ranks on Mira@ANL (BG/Q)

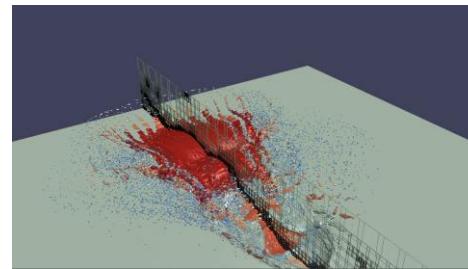


256K MPI ranks on Mira@ANL (IBM BG/Q)

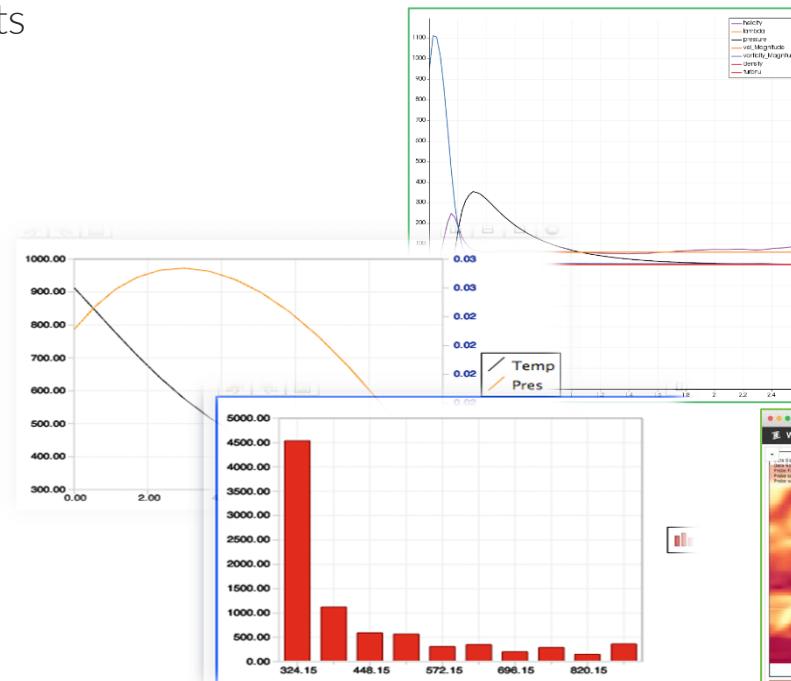
>CATALYST

>> Output Types

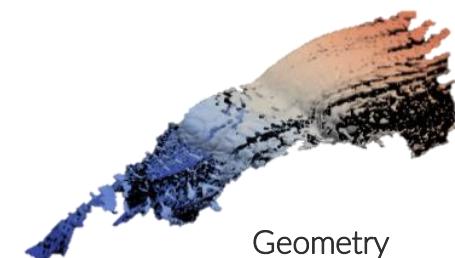
- Images
 - Static Images
 - Explorable Images
 - Charts
 - Geometry extracts
 - VTK parallel formats
 - ADIOS format
 - Other formats
 - ASCII output
 - Single quantities
 - Statistics



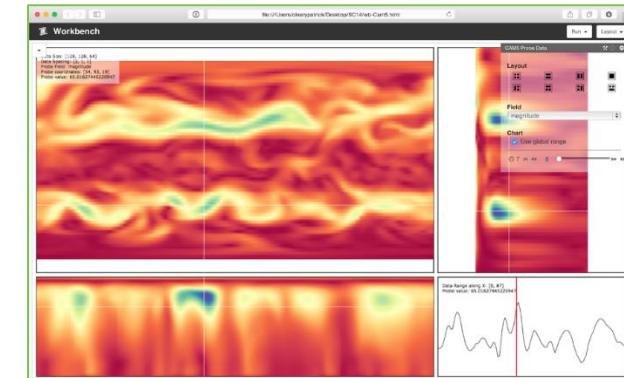
Rendered Images



Series Data



Geometry Extracts

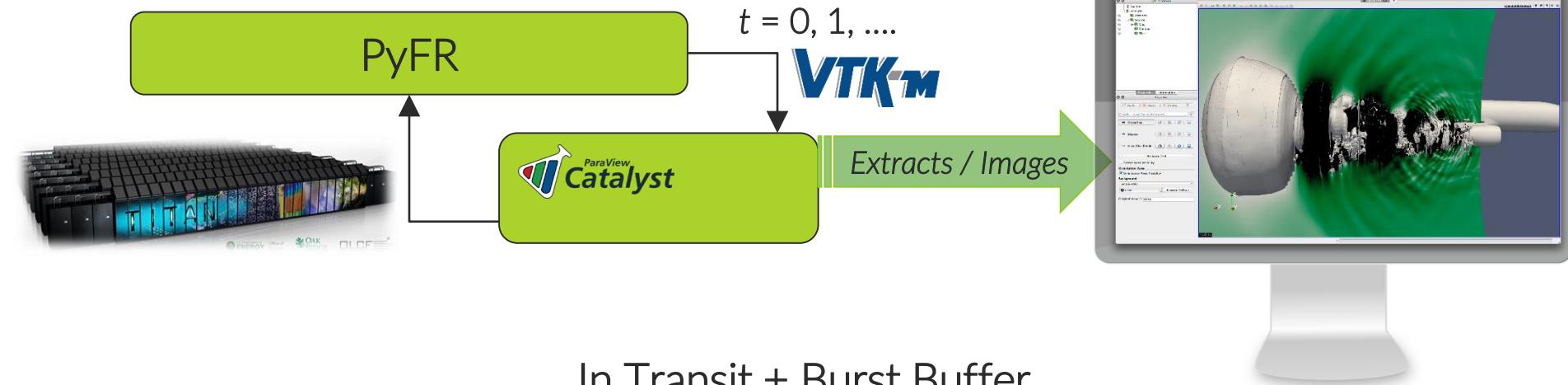




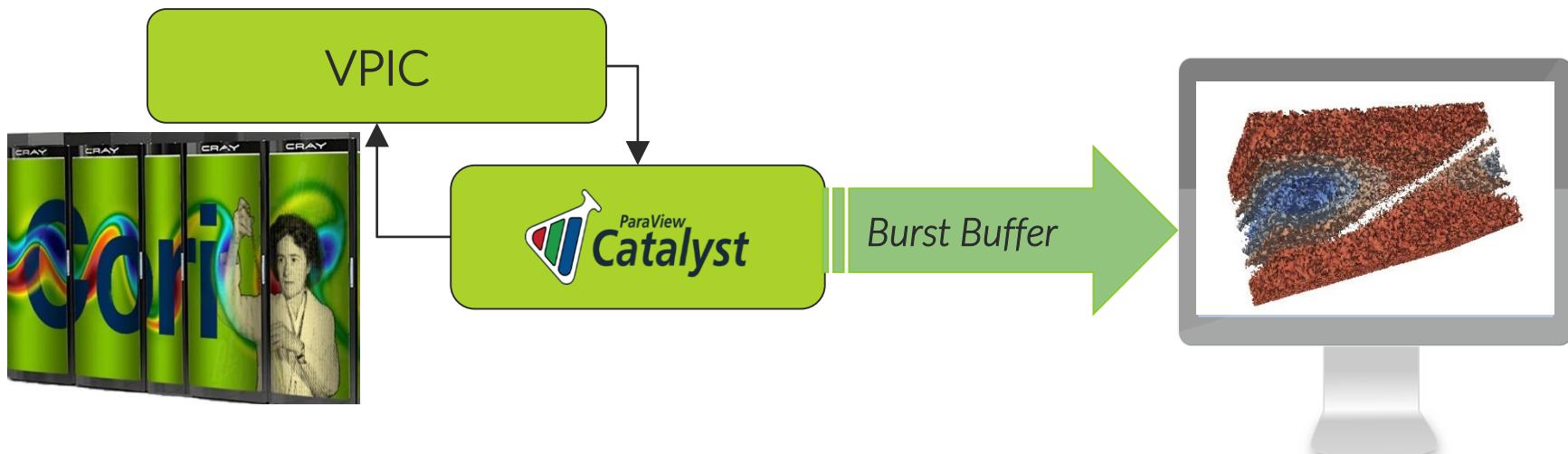
>CATALYST + VTK-M

>> Large scale in0sity

Live + VTK-m



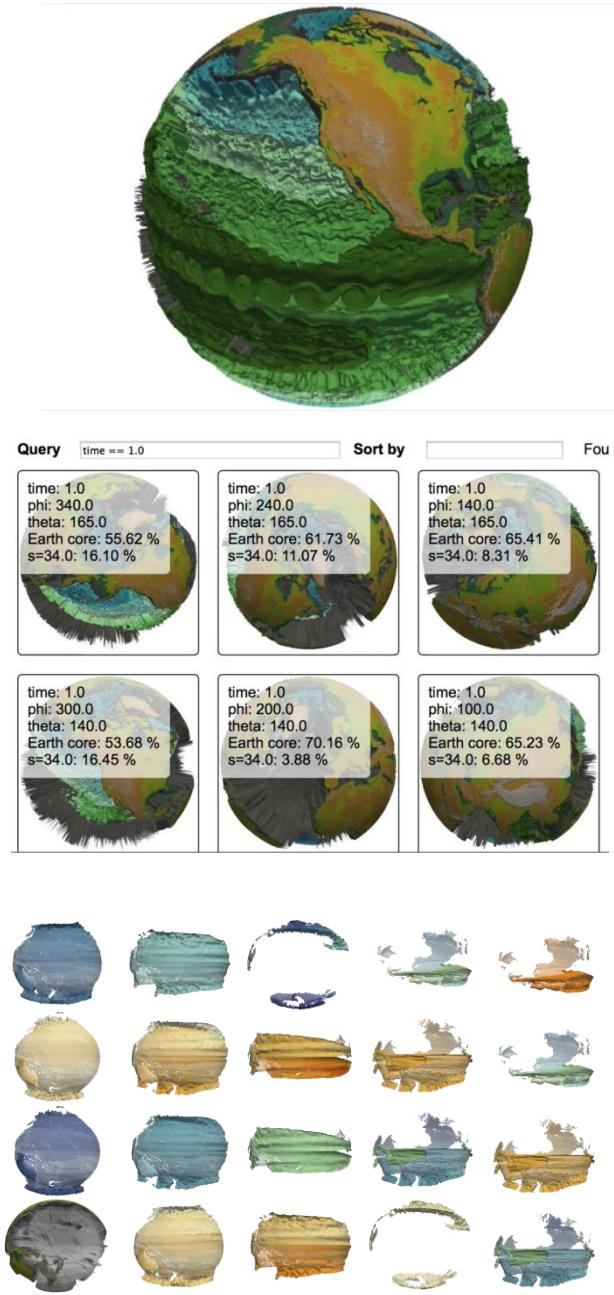
In Transit + Burst Buffer



>CINEMA

>> Image-based rendering

- Image-based rendering
- Interactive exploration
- Query images based on
 - View
 - Time
 - Objects
- Composite images
- <http://cinemascience.org>





Thanks

Questions ?

www.kitware.eu
julien.jomier@kitware.com

